

Tracy A. Heath



Probabilistic graphical models

Probabilistic Graphical Models

A representation of a model as a directed acyclic graph that exposes all of the assumptions and conditional dependence structure



Höhna et al. 2014. RevBayes: Probabilistic graphical model representation in phylogenetics. *Systematic Biology*. (doi: 10.1093/sysbio/syu039)

Probabilistic Graphical Models

This model: observed sequence data are generated by a Jukes-Cantor substitution process, with a uniform distribution over topologies and branch lengths drawn from an exponential distribution



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A probabilistic graphical model is a visual representation of the model structure

The elements of the graph denote the different kinds of variables in the model



li

 $\lambda = 10$

U

N = 127

 $\in 2N$

Constant node:

"equals"

represents a fixed value that is asserted or known

value of a prior parameter

$$\lambda$$
 <- 10

dimension of a N <- 127 parameter



Stochastic node:

"distributed by"

represents a random variable that is unknown and estimated

 $l_i \sim Exponential(\lambda)$

parameters that have a distribution

parameters

Deterministic node:

"determined by"

represents an unknown random variable estimated



2N-3

i=1

 $L := \sum l_i$

Observed stochastic node: "distributed by"

represents a random variable that is the observed outcome of the model and fixed to observed value



Plate: repetition

repeats model structure to simplify visualization



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repeats model structure to simplify visualization



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Probabilistic Graphical Models



Jukes-Cantor Model

Substitution model: with equal rates of substitution between bases and equal base frequencies



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(based on slides by M. Landis: http://bit.ly/2Hzr9Hu)

Kimura 2-Parameter Model

Transitions happen at a higher rate than transversions and equal base frequencies



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HKY Model

Transitions happen at a higher rate than transversions, with unequal base frequencies



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General Time Reversible Model

Unequal substitution rates and unequal base frequencies



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$_{R} =$	(—	$r_{AC}\pi_C$	$r_{AG}\pi_G$	$r_{AT}\pi_T$
		$r_{AC}\pi_A$	—	$r_{CG}\pi_G$	$r_{GT}\pi_T$
		$r_{AG}\pi_A$	$r_{CG}\pi_C$	—	$r_{GT}\pi_T$
	ſ	$r_{AT}\pi_A$	$r_{CT}\pi_C$	$r_{GT}\pi_G$	_

```
alpha <- [1, 1, 1, 1]
pi ~ dnDirichlet(alpha)
beta <- [1, 1, 1, 1, 1, 1]
r ~ dnDirichlet(beta)
Q := fnGTR(pi, r)
```

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Model Modularity



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